ADDENDUM TO THE PAPER "CENTRAL QUADRICS IN THE EUCLIDEAN $n$-SPACE"

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ABSTRACT. In this paper we give some proofs on the topic of the paper "Central quadrics in the Euclidean $n$-space". For example we give a more detailed description of the construction of Chasles and the wire (thread) model of Staude, respectively.

This paper is not self-contained. I suggest to look at the paper [3] for the necessary definitions and theorems.

1. Apollonius

Theorem 1 (Theorem of Apollonius). An ellipsoid in the Euclidean $n$-space has $n$ associated scalars invariants with respect to any affinity of the space. It can be defined by the formulas:

$$v_k := \sum_{i_1 < i_2 < \cdots < i_k} \det G[x^{i_1}, \cdots, x^{i_k}],$$

where $\{x^1, \ldots, x^n\}$ is a complete conjugate system of semi-diameters and $G[x^{i_1}, \cdots, x^{i_k}]$ is the Gram matrix of the vector system $x^{i_1}, \cdots, x^{i_k}$.

Proof. Consider the matrix $X^T X + tI$ where $t$ is a real number and $I$ is the identity matrix. Then we have

$$\det [(X^T X + tI)] = \det [A^2 + tI] = \sum_{k=0}^{n} t^{n-k} \prod_{i_1 < \cdots < i_k} a_{i_1}^2 \cdots a_{i_k}^2.$$ 

On the other hand, if $X^T X =: G = [g_{i,j}]$ is the Gram matrix of $X$, and $G_{i_1, \ldots, i_k}$ denotes its $k$-minor defined by the elements in the crossing of those rows and columns which correspond to the multi-index $\{i_1, \ldots, i_k\}$, than using an inductive argument and the rule on the addition of determinants we can prove that

$$\det [(G + tI)] = \sum_{k=0}^{n} t^{n-k} \sum_{i_1 < \cdots < i_k} \det [G_{i_1, \ldots, i_k}].$$

These two formulas imply that for all sets of complete conjugate systems hold the equality

$$v_k = \prod_{i_1 < \cdots < i_k} a_{i_1}^2 \cdots a_{i_k}^2,$$

which gives our statement. □

Statement 1 (The Apollonian pedal curve). Consider the set of homothetic ellipsoids $E(\lambda) = \{x \in \mathbb{R}^n : \sum_{i=1}^{n} (x_i/\lambda a_i)^2 = 1\} \lambda \in \mathbb{R}^+$ and a point $P = (u_1, \ldots, u_n)^T$ of the space. The locus of those points of the ellipsoids which are nearest to $P$ is a curve of order $n$ which we call Apollonian curve of the system of the homothetic system.

Remark 1. If $n = 2$ the above Apollonian curve is the so-called Apollonian equilateral hyperbola. As we know from the book [1] it is also the locus of the centers of the elements of that pencil of conics which determined by the given ellipse $E$ and a fixed circle which center is $P$ and intersects $E$ in four points. An immediate proof of this fact is the following. If a point $Q$ of the plane is a center of a conic of the pencil, then its polar lines with respect to the given ellipse and circle are parallel to each other. In fact, for any point $Q$ there is a point $Q'$ in the projective plane that the polar of $Q$ with respect to the element of the pencil are go through $Q'$. Since the polar of $Q$ is the ideal line if it is a center of a conic from the pencil, hence the point $Q'$ is also an ideal one. Since the polar of a point with respect to a circle is perpendicular
to the segment connecting the point with the center of the circle this common direction of the two polar lines is known. Hence the locus does not depend on the radius of the circle, it only depends on the ellipse and the given point. Consider now such a center $Q$ which is on the ellipse $E$. The polar $q$ of $Q$ with respect to $E$ is the tangent of $E$ at $Q$ hence it is perpendicular to $QP$ showing that $Q$ is on the Apollonian hyperbola $A_2(\tau)$. Clearly, $A_2(\tau)$ contains also the center of $E$ and the point $P$. We prove that the locus is a conic implying that it is agree the Apollonian hyperbola as we stated. In fact, if $Q'$ and $R'$ are the ideal points corresponding to the above connection to the centers $Q$ and $R$, respectively, the polars of $Q'$ and $R'$ with respect to the conics in the pencil go through $Q$ and $R$, respectively. If $S'$ any further (ideal) point of the line $Q'R'$ then its polar $s'_Q$ with respect to the conic with center $Q$ and its polar $s'_R$ with respect to the conic with center $R$ intersect in a point $S$ which is conjugate to $S'$. Of course $S$ is a center of a conic of the pencil. In this way, we got two pencils of lines with support $Q$ and $R$ are in a projective (but not perspective) connection and the corresponding elements intersect each other in the points $S$ of the searched locus, hence the locus by the Steiner’s definition of conics is a conic. Observe that those ideal points which are giving by the directions of the axes of the ellipse are points of the locus, too since their polar lines with respect to the ellipse and the circle are parallel to each other. Hence the above conic is such a hyperbola which has (at least) five common points with the Apollonian hyperbola implying that the two conics are agree.

2. Famous applications in dimension three

The formulas of the previous sections gives a good frame to prove some known results in the three-space. In this section we examine three such problems.

2.1. Right cones and focal conics. The following theorem can be used in mechanics, descriptive geometry and pure geometry of the three-dimensional space, respectively.

**Theorem 2** (See e.g. [6]). Let $n = 3$. The locus of the apices of right cones through a real focal quadric is the other real focal quadric.

**Proof.** To find the locus of the vertices of right cones which can envelope a focal quadric we consider the canonical equation of the cone through to $C_k$ with apex $x'$ ((27) in [3])

$$\sum_{i=1}^{n} \frac{x_i^2}{s_{i,k}^2} = 0.$$ 

It may represent a right cone if $n-1$ from the above coefficients are equals. Since for a fixed $k$ the numbers $(s_{i,k}^2)$ are the distinct roots of the polynomial equation (10) in [3], two of them could be equal to each other if and only if $f((s_{i,k}^2)^2) = 0$ for an index $j = 2, \ldots, n$ implying that it is the square of two consecutive semi-axes from $a_2, \ldots, a_n$ which are equal to each other; hence either $(s_{i,k}^2)^2 = (a_j)^2 = (a_{j+1})^2 = (s_{k+1,j}^2)^2$ or $(s_{i,k}^2)^2 = (s_{j,k}^2)^2 = (a_{j-1})^2 = (a_j)^2$ hold. (In both of these cases the index $k$ distinct from the other two ones.) This means that the vertex $x'$ of the cone by definition is a real point of a focal quadric. In the first case, if $x_{j'} = 0$ then it is on $C_j$ and if $x_{j'+1} = 0$ then it is on $C_{j+1}$. On the other hand if e.g. we assume that $(s_{i,k}^2)^2 = (s_{k+1,j}^2)^2 (j, j+1 \neq k)$ then the examined cone with vertex $x'$ and through $C_k$ has canonical form

$$C_k(x') : \sum_{i,j=1}^{j-1} \frac{x_{j}^2}{(s_{i,k}^2)^2} + \frac{x_{j}^2}{(s_{k}^2)^2} + \frac{x_{j+1}^2}{(s_{k}^2)^2} = 0$$

showing that it has two semi-axes which are equal to each other.

In the three-dimensional case for $k = 3$ the index $j$ may be 1 or 2. Since $C_1$ has no real point we know that $C_2$ contains the vertex of $C_3(x')$ and the latter is a right cone and vice versa. The equations of the two focal conics are

$$C_3 : \left\{ \frac{x_1^2}{a_1^2 - a_3^2} + \frac{x_2^2}{a_2^2 - a_3^2} = 1, x_3 = 0 \right\} \quad \text{and} \quad C_2 : \left\{ \frac{x_1^2}{a_1^2 - a_2^2} + \frac{x_2^2}{a_3^2 - a_2^2} = 1, x_2 = 0 \right\}$$

and the canonical equation of the right cone through $C_3$ and with the vertex $x' \in C_2$ is

$$\frac{x_1^2}{a_1^2} + \frac{x_2^2}{a_1^2} + \frac{x_3^2}{a_3^2} = 0.$$
2.2. Chasles’s construction on conjugate diameters. The standard proof of Rytz construction based on the so-called ”two-circle figure” (see in Fig. 1) in which we draw the incircle and the circumcircle of the ellipse. The same figure with a little modification enable to get another construction to solve this problem.

In fact, let the line $PM$ be the normal of the ellipse at $P$. This is perpendicular to $OQ$ hence it is parallel to $OQ^*$. If $M$ is the intersection of this normal with the line $OK$ (as in the standard proof $Q^*$ is the rotated copy of $OQ$ by $\pi/2$ and $K$ is the middle point of the segment $PQ^*$), then the triangles $OTQ^*$ and $MP^*P$ are congruent to each other. From this we get that $PM$ is congruent to $OQ^*$. Let $L$ be the reflected image of $M$ at $P$. Since $PL$ is parallel and equal to $OQ^*$, $OL$ is also parallel and congruent to $Q^*P$. Hence the axis $AB$ of the ellipse is the bisector of the angle $LOM\angle$. The other axis of the ellipse is perpendicular to $AB$ at $O$, and if we draw parallels from $P$ to these axes we get the points $T$ and $P'$ as the intersections of the line $OM$ with these parallels, respectively. Clearly, the lengths of $OT$ and $OP'$ are equals to the lengths of the semi-axes, respectively. The construction has the following steps:

- Draw perpendicular to line $OQ$ from $P$ and determine the points $M$, $L$ on this line by the property $|PM| = |PL| = |OQ|$. 
- Draw the bisectors of the angle $LOM\angle$, these are the axes of the ellipse.
- Draw parallels to these bisectors from the point $P$ and determine the intersections of these lines with the line $OM$ ($T$, $P'$). The lengths of the semi-axes are the lengths of the segments $OT$, $OP'$, respectively.

Observe that $L$ and $M$ determine a tangential pencil of confocal conics in the plane. From these pencils there are two conics an ellipse and a hyperbole through the point $O$. By the bisection property, the tangent lines of these conics at $O$ are the axes of the searching ellipse. If we visualize the union of lines $OM$ and $OL$ as a cone with apex $O$ and through the focal figure of the confocal system of conics determined by the points $M$ and $L$ then the axes of the ellipse are equals the axes of this cone. Hence this construction contains only such concepts whose analogous exist in higher dimensions, too.

Let us follow our investigations in the three-space. Our purpose to give a construction, which determine the axes of an ellipsoid from a complete system of conjugate diameters. To this consider the three pairwise conjugate semi-diameters $OP, OQ$ and $OR$, respectively. The construction of Chasles (see in [2] or [7]) contains the following steps:

- Determine the three mutually perpendicular line through $P$, one of its the normal of the ellipsoid (perpendicular to the plane $(OQR)$ at $P$) and the other two are parallel to the axes of the ellipse $E$ which is the intersection of the plane $(OQR)$ by the given ellipsoid. (By the above construction we can get these lines.)
- They contains the axes of a confocal system of quadrics dual to the confocal system of the given ellipsoid. By Statement 1 in [3] the axes of this systems can be given by the system $\{a_1^2, a_2^2, a_3^2\}$ as respective lengths of the semi-axes. The square of the semi-axes of the focal conics of this system
are \( \{a_1^4 - (a_3^2)^2, (a_3^2)^2 - (a_1^2)^2\} \): \( \{a_1^2 - (a_3^2)^2, (a_3^2)^2 - (a_1^2)^2\} \) giving an ellipse and a hyperbola, respectively. The square of the axes of \( E \) are \( (a_1^2)^2 = (a_1^2)^2 - (a_3^2)^2 \) and \( (a_2^2)^2 = (a_1^2)^2 - (a_3^2)^2 \).

These values are known from the construction, hence we can give also the squares of the lengths of the semi-axes of the focal conics.

- The intersection of the two focal cones with apex \( O \) is the union of four common edges, the six planes determining by these edges intersect to each other in three mutual perpendicular lines which are the three axes of these two confocal cones. To prove this statement observe that the two focal cones are confocal quadrics and so they principal axes are common in their directions. The three principal axis intersects a plane of intersection in three points which are form an autopolar triangle of this plane with respect to the two intersection conics by the two focal cones. The four common points of the two conic of intersections determines that quadrangle which diagonal points form the only autopolar triangle with respect to both of the conics. By Statement 6 in [3] these are the searched axes of the given ellipsoid, while the planes through \( P \) and parallel to the principal planes of the ellipsoid cut off on these four lines parts equal in length to the semi-axes by Statement 7 in [3].

Observe that this theoretical construction cannot be constructed with ruler and compass in general, because the construction of the common lines of two cones of second order implies the construction of the common points of two conics, which is some cases unconstructible. More details on this problem can be found in [4].

2.3. **Staude's wire model in 3-space.** At the end of the eighteenth century O. Staude printed the book [8] with a lot of interesting results. H. D. Thompson wrote in his recension on the book the following: Possibly the most interesting, although not the most general of the focal properties which Professor Staude deduces, are the following. (The "focal distance" from any point to the focus of the one of a pair of focal conics is defined as the shortest distance on the broken line to a point on that conic, and thence to the adjacent focus). In an ellipsoid, for any point on the surface, the sum of the focal distances to a focus of the focal ellipse and to the opposite focus of the focal hyperbola is a constant. And the normal to the surface at the point bisects the angle of the two lines. This theorem is the basis of the well-known wire model, No. 110 of the Brill collection, which represents the two focal curves of the system by wires rigidly connected, and which has a string fastened so as to represent the sum of the focal distances of the theorem. This result can be cited without proof in the book of Hilbert and Cohn-Vossen [5], too.

**Lemma 1.** Let \( r(u_1, \ldots, u_{n-1}) = (x_1(u_1, \ldots, u_{n-1}), \ldots, x_n(u_1, \ldots, u_{n-1})) \) be a hypersurface of the \( n \)-dimensional Euclidean space. \( F \) and \( P \) are two points of the space and \( Q \) is a point of the surface for which the length of the broken line \( FQ\!P \) is minimal. Then the angles between the normal vector of the surface at its point \( Q \) and the respective segments \( FQ \) and \( QP \) are equal to each other.

**Proof.** Denote the coordinates of \( F \) and \( P \) by \( (f_1, \ldots, f_n)^T \) and \( (p_1, \ldots, p_n)^T \), respectively. We also denote by \( f = \sum_{i=1}^{n} (x_i - f_i)^2 \) and \( g = \sum_{i=1}^{n} (x_i + p_i)^2 \) the functions \( |FP|^2 \) and \( |PQ|^2 \), respectively. Then the partial derivatives of the length function \( \sqrt{f^2 + g^2} \) of variable \( u_1, \ldots, u_n \) have to vanish implying the equalities:

\[
0 = \frac{\partial f}{\partial u_i} + \frac{\partial g}{\partial u_i} = \frac{\sum_{j=1}^{n} (x_j - f_j) \frac{\partial x_j}{\partial u_i}}{|FQ|} - \frac{\sum_{j=1}^{n} (x_j - p_j) \frac{\partial x_j}{\partial u_i}}{|PQ|} = \sum_{j=1}^{n} \left( \frac{(x_j - f_j) - (x_j - p_j)}{|FQ|} \right) \frac{\partial x_j}{\partial u_i}
\]

for all \( i = 1, \ldots, (n-1) \). Hence \( FQ/|FQ| - PQ/|PQ| \) orthogonal to \( n - 1 \) independent vectors of the tangent hyperplane at the searched point \( Q \) meaning that it is parallel to the normal of the hypersurface at this point \( Q \). Since the vectors \( FQ/|FQ| \) and \( PQ/|PQ| \) are unit vectors this proves the lemma. \( \square \)

The following result can be found in [6], too.

**Lemma 2.** Assume that \( H_1 \) and \( H_2 \) are two points on the same branch (on the different branches) of the focal hyperbola and \( E \) is any point of the focal ellipse. Then the difference \( |H_1E| - |EH_2| \) (the sum \( |H_1E| + |EH_2| \) of the lengths of the edges of the broken line \( H_1EH_2 \) is independent from the position of \( E \). Similarly if \( E_1 \) and \( E_2 \) are two points on the focal ellipse then the difference \( |H_1E| - |HE_2| \) of the broken line \( E_1HE_2 \) is independent from the position of \( H \) in the focal hyperbola.

**Proof.** Using the notation of Example 1 in [3] the focal ellipse contains that points of the space which are of the form \((\sqrt{a^2 - c^2} \cos u, \sqrt{b^2 - c^2} \sin u, 0)^T \) for \( 0 \leq u < 2\pi \) and the points of the two branches of the
focal hyperbola have the coordinates $(\pm \sqrt{a^2 - b^2 \cosh v}, 0, -\sqrt{b^2 - c^2 \sinh v})^T$. If $H_1$ are the same branch of the hyperbola then we have

$$|H_1E| - |EH_2| = \sqrt{(\sqrt{a^2 - c^2 \cos u} \mp \sqrt{a^2 - b^2 \cosh v_1})^2 + (b^2 - c^2 \sin^2 u + (b^2 - c^2) \sinh^2 v_1} -$$

$$= \sqrt{(a^2 - b^2) \cos^2 u \mp 2\sqrt{a^2 - c^2 \cos u \sqrt{a^2 - b^2 \cosh v_1} + (a^2 - c^2) \cosh^2 v_1} -$$

$$= \sqrt{(a^2 - b^2) \cos^2 u \mp 2\sqrt{a^2 - c^2 \cos u \sqrt{a^2 - b^2 \cosh v_2} + (a^2 - c^2) \cosh^2 v_2} =$$

$$= |\sqrt{a^2 - b^2 \cos u \pm a^2 - c^2 \cosh v} - |\sqrt{a^2 - b^2 \cos u \mp a^2 - c^2 \cosh v}.$$  

Since $\sqrt{a^2 - c^2 \cosh v} \geq \sqrt{a^2 - b^2 \cos u}$ for all values $u$ and $v$ the terms containing the parameter $u$ are vanishing showing the truth of the statement in this case. The other two statements of the lemma can be proved similarly. □

**Lemma 3.** If $P$ is any point of the space and $l$ is a common transversal of the focal conics through $P$ with points of intersection $E \in C_3 \cap l$ and $H \in C_2 \cap l$ for which $E$ separates $P$ and $H$ (for which $H$ separates $P$ and $E$). Then for any point $H_1$ ($E_1$) on the same branch of the focal hyperbola (of the focal ellipse) as $H$ is, the minimal length of the broken line $PFH_1$ ($PFE_1$) from $P$ to $H_1$ ($E_1$) through a point $F$ of the focal ellipse (of the same branch of the focal hyperbola as $H$) attend at the point $E$ ($H$).

If $H$ separates the two points of intersection, then we have the inequality $|PE| - |EH_1| \leq |PF| - |FH_1|$.

**Proof.** $|PE| + |EH| \leq |PF| + |FH|$ for all points of $C_3$. $|HE| - |EH_1| = |HF| - |FH_1|$ implying that

$$|PE| + |EH_1| = |PE| + |EH| - (|EH| - |EH_1|) \leq |PF| + |FH| - (|FH| - |FH_1|) = |PF| + |FH_1|,$$

as we stated. The alternative statement in the brackets can be get with the same manner.

If $P$ separates $E$ and $H$ then $|EH| - |PE| \geq |FH| - |FP|$ and again $|HE| - |EH_1| = |HF| - |FH_1|$, hence $|PE| - |EH_1| \leq |PF| - |FH_1|$ as we stated. □

Now we are ready to prove Staude’s result on wire construction.

**Theorem 3.** Let $P$ be a point of the ellipsoid $E$ given by the canonical form

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1.$$  

Denote by $F_1 = (-\sqrt{a^2 - c^2}, 0, 0)^T$ the left focus of the focal hyperbola of the confocal quadrics defined by the given ellipsoid and $G_2 = (\sqrt{a^2 - b^2}, 0, 0)^T$ is the right focus of the focal ellipse of the same system. Then the sum of the shortest length of the broken line $F_1HPEG_2$ where $H$ is a point of the focal hyperbola and $E$ is a point of the focal ellipse is equal to $2a + \sqrt{a^2 - c^2} - \sqrt{a^2 - b^2}$ hence it is independent from the position of $P$ on the ellipsoid.

**Proof.** To prove this statement use first Lemma 3 to calculate that distances which are needed for us. The common transversals of the focal conics have the parametric representation

$$\xi = \varepsilon(\xi) \sqrt{\frac{b^2c^2}{\mu \nu}},$$

$$\eta = \varepsilon(\eta) \sqrt{\frac{(b^2 - \mu)(\mu - c^2)}{\mu(\nu - \mu)}},$$

$$\zeta = \varepsilon(\zeta) \sqrt{\frac{(\nu - b^2)(\nu - c^2)}{\nu(\nu - \mu)}}$$

with respect to the dual coordinate system with origin $P$ and having the normals of the confocals through $P$ as axes. Here $a_1 = a$, $a_2 = b$, $a_3 = c$; $(a_1^2)^2 = a^2 - \mu$, $(a_2^2)^2 = b^2 - \mu$, $(a_3^2)^2 = c^2 - \mu$; and $(a_1^2)^2 = a^2 - \nu$, $(a_2^2)^2 = b^2 - \nu$, $(a_3^2)^2 = c^2 - \nu$ with $c^2 < \mu < b^2 < \nu < a^2$. One of the signs $\varepsilon(\xi), \varepsilon(\eta), \varepsilon(\zeta)$ can be chosen.
arbitrarily. The coordinate transformation which connects the variable \( \xi, \eta, \zeta \) to the original variable \( x, y, z \) is

\[
\begin{align*}
  x - x' & = \left( \frac{p_0}{a^2} \xi + \frac{p_\mu}{a^2 - \mu} \eta + \frac{p_\nu}{a^2 - \nu} \right) x' \\
  y - y' & = \left( \frac{p_0}{b^2} \xi + \frac{p_\mu}{b^2 - \mu} \eta + \frac{p_\nu}{b^2 - \nu} \right) y' \\
  z - z' & = \left( \frac{p_0}{c^2} \xi + \frac{p_\mu}{c^2 - \mu} \eta + \frac{p_\nu}{c^2 - \nu} \right) z',
\end{align*}
\]

(3)

where the coordinates of the point \( P \) with respect to the original \( \{O, x, y, z\} \) system are \( x', y' \) and \( z' \), respectively and by (16) in [3]

\[
p_0 := \sqrt{\frac{a^2 b^2 e^2}{\mu \nu}}, \quad p_\mu = \sqrt{(a^2 - \mu)(b^2 - \mu)(\mu - c^2)} \quad \mu(\nu - \mu) = \frac{(a^2 - \nu)(\nu - b^2)}{\nu(\nu - \mu)},
\]

(4)

Hence the common edges with respect to the system \( \{O, x, y, z\} \) have the following form:

\[
\begin{align*}
  x - x' & = t \left( \epsilon(\xi) \frac{b^2 e^2}{\mu \nu} - \epsilon(\eta) \frac{(b^2 - \mu)(c^2 - \mu)}{\sqrt{a^2 - \mu \nu(\mu - \nu)}} + \epsilon(\zeta) \frac{(b^2 - \nu)(c^2 - \nu)}{\sqrt{a^2 - \nu \mu(\nu - \mu)}} \right) x' \\
  y - y' & = t \left( \epsilon(\xi) \frac{a^2 e^2}{\mu \nu} - \epsilon(\eta) \frac{\sqrt{a^2 - \mu(\mu - \nu)}}{\sqrt{a^2 - \mu(\nu - \mu)}} + \epsilon(\zeta) \frac{\sqrt{a^2 - \nu(\nu - \mu)}}{\nu(\mu - \nu)} \right) y' \\
  z - z' & = t \left( \epsilon(\xi) \frac{a^2 b^2}{\mu \nu} - \epsilon(\eta) \frac{\sqrt{a^2 - \mu(b^2 - \mu)} \nu - \epsilon(\zeta) \sqrt{a^2 - \nu(b^2 - \nu)} \mu}{\nu(\mu - \nu)} \right) z'.
\end{align*}
\]

(5)

The focal ellipse lying on the plane \( z = 0 \) implying that the corresponding possible parameters are

\[
t = \frac{-1}{\left( \epsilon(\xi) \frac{a^2 b^2}{\mu \nu} - \epsilon(\eta) \frac{\sqrt{a^2 - \mu(b^2 - \mu)} \nu - \epsilon(\zeta) \sqrt{a^2 - \nu(b^2 - \nu)} \mu}{\nu(\mu - \nu)} \right)} = \frac{\mu \nu(\nu - \mu)}{-\epsilon(\xi)ab^2(\nu - \mu) + \epsilon(\eta) \sqrt{a^2 - \mu(\nu - \mu)}(\nu - \epsilon(\zeta)) \sqrt{a^2 - \nu(\nu - \mu)}},
\]

which square gives the squared distance of \( P \) to the corresponding point \( E \) of the transversal by equation (26) in [3]. From this we get

\[
x = \frac{\frac{a^2 - c^2}{a^2}}{-\epsilon(\xi)ab^2(\nu - \mu) + \epsilon(\eta) \sqrt{a^2 - \mu(b^2 - \mu) \nu - \epsilon(\zeta) \sqrt{a^2 - \nu(b^2 - \nu) \mu}} x' =
\]

\[
\begin{align*}
  x' & = \frac{a^2 - c^2}{a^2 - \mu} \left( \frac{\epsilon(\xi) \sqrt{a^2 - \mu} \mu(b^2 - \mu)(\nu - \epsilon(\zeta)) \sqrt{a^2 - \nu(b^2 - \nu) \mu}}{\sqrt{a^2 - \mu b^2} \sqrt{a^2 - c^2}} \right) \\
  y' & = \frac{a^2 - c^2}{a^2 - \mu} \left( \frac{\epsilon(\eta) \left( \sqrt{a^2 - \mu} b^2 \sqrt{a^2 - \nu(b^2 - \nu) \mu} \right) \sqrt{a^2 - \mu \nu(b^2 - \nu) \mu}}{\sqrt{a^2 - \mu b^2} \sqrt{a^2 - c^2}} \right) \\
  z' & = \frac{a^2 - c^2}{a^2 - \mu} \left( \frac{\epsilon(\zeta) \left( \sqrt{a^2 - \mu} b^2 \sqrt{a^2 - \nu(b^2 - \nu) \mu} \right) \sqrt{a^2 - \mu \nu(b^2 - \nu) \mu}}{\sqrt{a^2 - \mu b^2} \sqrt{a^2 - c^2}} \right),
\end{align*}
\]

where \( \epsilon(x') \) is the sign of \( x' \) and we used here equation (12), too. For brevity denote by the long fraction by \( B/A \) meaning that

\[
x := \epsilon(x') \frac{\sqrt{a^2 - c^2} \sqrt{a^2 - \mu} \mu(b^2 - \mu)(\nu - \epsilon(\zeta)) \sqrt{a^2 - \nu(b^2 - \nu) \mu}}{\sqrt{a^2 - \mu b^2} \sqrt{a^2 - c^2}}.
\]

Applying in the plane \( z = 0 \) the equation (12) for the focal ellipse we get that there is a constant \( e \) for which \( b^2 \leq e^2 \leq a^2 \) and

\[
x = \epsilon((C_3)_x) \frac{\sqrt{a^2 - c^2} \sqrt{a^2 - \mu} \mu(b^2 - \mu)(\nu - \epsilon(\zeta)) \sqrt{a^2 - \nu(b^2 - \nu) \mu}}{\sqrt{a^2 - \mu b^2} \sqrt{a^2 - c^2}} \quad \text{and} \quad y = \epsilon((C_3)_y) \frac{\sqrt{b^2 - c^2} \sqrt{a^2 - \nu(b^2 - \nu) \mu}}{\sqrt{a^2 - \mu b^2} \sqrt{a^2 - c^2}}
\]

where \( \epsilon((C_3)_x) \) is the sign of the coordinate \( x \). This implies the equality:

\[
\epsilon(x') \epsilon((C_3)_x) \sqrt{a^2 - e^2} = \frac{B}{A}.
\]
On the other hand we have the identity
\[
\varepsilon(\xi)\varepsilon(\eta)B + (\varepsilon(\xi)a + \varepsilon(\eta)\sqrt{a^2 - \mu} + \varepsilon(\zeta)\sqrt{a^2 - \nu})A =
\]
\[
= -\varepsilon(\eta)\varepsilon(\zeta)b^2(\nu - \mu)\sqrt{a^2 - \mu} + \varepsilon(\xi)\varepsilon(\eta)(b^2 - \mu)\nu - \varepsilon(\xi)\varepsilon(\eta)(b^2 - \nu)a\sqrt{a^2 - \mu} +
\]
\[
+ (\varepsilon(\xi)a + \varepsilon(\eta)\sqrt{a^2 - \mu} + \varepsilon(\zeta)\sqrt{a^2 - \nu})(-\varepsilon(\xi)\eta(\nu - \mu) + \varepsilon(\eta)\nu(\nu - \mu))\sqrt{a^2 - \mu} + \varepsilon(\xi)\varepsilon(\eta)(b^2 - \nu)a\sqrt{a^2 - \mu} +
\]
\[
= \varepsilon(\eta)(-b^2(\nu - \mu) - (b^2 - \mu)\nu + (b^2 - \mu)\nu\sqrt{a^2 - \mu} - \mu + \varepsilon(\xi)\varepsilon(\eta)(b^2 - \nu)a\sqrt{a^2 - \mu} +
\]
\[
+ \varepsilon(\xi)\varepsilon(\eta)(\nu(\nu - \mu) - (b^2 - \nu)\mu - b^2(\nu - \mu))\sqrt{a^2 - \mu} +
\]
\[
+ \varepsilon(\xi)\varepsilon(\eta)(\nu(\nu - \mu) - (b^2 - \nu)\mu - b^2(\nu - \mu))\sqrt{a^2 - \mu} +
\]
\[
- a^2b^2(\nu - \mu) + (a^2 - \mu)(b^2 - \nu)(a^2 - \nu)(b^2 - \nu) = \mu^2 - \nu^2 = \nu
\]

implying the result:
\[
(6) \quad t = \frac{\mp \nu(\nu - \mu)}{A} = -\varepsilon(\xi)a - \varepsilon(\eta)\sqrt{a^2 - \mu} - \varepsilon(\xi)\sqrt{a^2 - \nu} - \varepsilon(\xi)\varepsilon(\eta)(\varepsilon(\eta)(\varepsilon(\eta)(\varepsilon(\xi)\varepsilon(\zeta)))(\varepsilon(3)(x))\varepsilon(3) - \mu^2 - \nu^2 = \nu
\]

Similarly the focal hyperbola is lying on the plane \( y = 0 \). Hence we have in this case that
\[
\tau = \frac{\pm \nu(\nu - \mu)}{a}
\]
and also
\[
\ddot{x} = \varepsilon(x')\frac{\sqrt{a^2 - \nu^2}}{\sqrt{a^2 - \nu^2}}
\]
\[
\frac{-\varepsilon(\xi)c^2(\nu - \mu)\sqrt{a^2 - \mu} + \varepsilon(\eta)c^2(\nu - \mu)a\sqrt{a^2 - \mu} - \varepsilon(\xi)c^2(\nu - \mu)a\sqrt{a^2 - \mu} =
\]
\[
-\varepsilon(\xi)c^2(\nu - \mu) + \varepsilon(\eta)c^2(\nu - \mu)a\sqrt{a^2 - \mu} - \varepsilon(\xi)c^2(\nu - \mu)a\sqrt{a^2 - \mu} =
\]
\[
= \varepsilon(x')\frac{\sqrt{a^2 - \nu^2}}{D} \sqrt{a^2 - \nu^2} = \frac{D}{C}
\]

For the coordinates of the focal hyperbola by (12) hold that
\[
\ddot{x} = \varepsilon((C_2)_x)\frac{\sqrt{a^2 - \nu^2}}{\sqrt{a^2 - \nu^2}}, \quad y = 0 \quad \text{and} \quad z = \varepsilon((C_2)_z)\frac{\sqrt{b^2 - c^2}}{\sqrt{a^2 - \nu^2}}
\]

hence we have
\[
\varepsilon(x')\varepsilon((C_2)_\ddot{x})\varepsilon(a^2 - \nu^2) = \frac{D}{C}
\]

Clearly the identity
\[
\varepsilon(\xi)\varepsilon(\eta)\varepsilon(\zeta)D + (\varepsilon(\xi)a + \varepsilon(\eta)\sqrt{a^2 - \mu} + \varepsilon(\zeta)\sqrt{a^2 - \nu})C = -\mu(\nu - \mu)
\]
is also hold, and thus
\[
(7) \quad \tau = \frac{\pm \nu(\nu - \mu)}{C} = -\varepsilon(\xi)a - \varepsilon(\eta)\sqrt{a^2 - \mu} - \varepsilon(\xi)\sqrt{a^2 - \nu} - \varepsilon(\xi)\varepsilon(\eta)(\varepsilon(\eta)(\varepsilon(\xi)\varepsilon(\zeta)))(\varepsilon(3)(x))\varepsilon(3) - \mu(\nu - \mu)
\]

For a given position of the point \( P \) choose that four combinations for the eight possible ones that the four intersection points on the focal ellipse correspond to positive parameter values, respectively. It is easy to see\(^1\) that in this case we have to choose the following combination of signs:

<table>
<thead>
<tr>
<th>( \varepsilon(\xi) )</th>
<th>( \varepsilon(\eta) )</th>
<th>( \varepsilon(\zeta) )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( r_1 )</td>
<td>-1</td>
<td>1</td>
</tr>
<tr>
<td>( r_2 )</td>
<td>-1</td>
<td>-1</td>
</tr>
<tr>
<td>( r_3 )</td>
<td>-1</td>
<td>-1</td>
</tr>
<tr>
<td>( r_4 )</td>
<td>-1</td>
<td>1</td>
</tr>
</tbody>
</table>

The corresponding common transversals we call the focal radii \( r_i \) of the point \( P \) to the focal conics.

In this case, we can compare the positions of the points \( E \) and \( H \) on a focal radius by the parameter values \( t \) and \( \tau \). If \( \tau > t > 0 \) then the point \( E \) separates the point \( P \) and \( H \) and if \( t > \tau \) then either \( H \) separates \( P \) and \( E \) or \( P \) separates \( E \) and \( H \), respectively. Consider the difference
\[
\frac{1}{\tau} - \frac{1}{t} = -\frac{b^2 - c^2}{\mu(\nu - \mu)} \left( -\varepsilon(\xi)(\nu - \mu) + \varepsilon(\eta)(\nu(\nu - \mu) - \varepsilon(\xi)\sqrt{a^2 - \nu^2} \right) =
\]

\(^1\) We have to prove that the equality \( ab^2(\nu - \mu) > \sqrt{a^2 - \mu}(b^2 - \mu)\nu + \sqrt{a^2 - \nu}(b^2 - \nu)\mu \) fulfill if \( c^2 < \mu < b^2 < \nu < a^2 \) hold for the corresponding parameters.
with respect to that corresponding to the same branch of the focal hyperbola we have \( \varepsilon \) if \( H \neq \varepsilon \) respectively. From this we get that with respect to the fact that \( r \tau < 0 \) then \( P \) separates the two intersection points to each other. In the case of \( i = 3,4 \) \( \tau \) is always positive the two points of intersections are on the same radius and the point of the focal hyperbola separates the point \( P \) and the point of the focal ellipse. For \( i = 3 \) the numerator \( D \) of \( r_3 \) is negative and the same value for \( r_4 \) is positive. Since the denominator \( C \) is positive in both of these cases, the corresponding points of the focal hyperbola have opposite half-spaces with respect to the \( yz \)-plane. Hence in the case of \( r_3 \) \( \varepsilon((C_2)_x) = -\varepsilon(x') \) and in the case of \( r_4 \) \( \varepsilon((C_2)_x) = \varepsilon(x') \), respectively. Since for \( r_1 \) \( D \) is positive and for \( r_2 \) \( D \) is negative then the sign dependent from the relative position of the point \( P \) and the points of the focal hyperbola. For \( r_1 \) with respect to the fact that \( \tau \) is positive or negative, \( P \) has to the same or the opposite half-space as the point of the focal hyperbola. Conversely, for \( r_2 \) the point of the focal hyperbola lies in the opposite or same half-space as \( P \) with respect to the fact that \( t \) and \( x' \) positive or negative, respectively. By formula we have that in the case of \( r_1 \) \( \varepsilon((C_2)_x) = \varepsilon(x') \) and in the case of \( r_2 \) \( \varepsilon((C_2)_x) = -\varepsilon(x') \).

Hence the broken line \( PEG_2 \) can be realised with focal radii \( r_1 \) or \( r_2 \) meaning that either

\[
|PE| = t = a - \sqrt{a^2 - \mu} + \sqrt{a^2 - \nu} + \varepsilon(x')\varepsilon((C_3)_x)\sqrt{a^2 - c^2}
\]

in the case of \( r_1 \) or

\[
|PE| = t = a - \sqrt{a^2 - \mu} + \sqrt{a^2 - \nu} - \varepsilon(x')\varepsilon((C_3)_x)\sqrt{a^2 - c^2}
\]

in the case of \( r_2 \), respectively. For the distance of \( E \) and \( G_2 \) we have

\[
(EG_2)^2 = \left( \frac{\varepsilon(a^2 - c^2)\sqrt{a^2 - c^2}}{\sqrt{a^2 - b^2}} - \sqrt{a^2 - b^2} \right)^2 + \left( \frac{\varepsilon(a^2 - c^2)\sqrt{a^2 - c^2}}{\sqrt{a^2 - b^2}} - \sqrt{a^2 - b^2} \right)^2 =
\]

\[
= (-c^2 + (a^2 - b^2) + (a^2 + b^2) + (-c^2) - 2\rho\sqrt{(a^2 - c^2)(a^2 - e^2)} =
\]

\[
= \left( \sqrt{a^2 - c^2} - \rho\sqrt{a^2 - e^2} \right)^2,
\]

where \( \rho \) is +1 if \( E \) and \( G_2 \) are in the same half-space with respect to the plane \( yz \) and -1 in the other case. From this we get that with respect to the fact that \( G_2 \) and \( P \) are the same or opposite half-spaces we get the optimal polygonal lengths:

\[
|PE| + |EG_2| = a - \sqrt{a^2 - \mu} - \varepsilon\sqrt{a^2 - \nu} + \sqrt{a^2 - c^2},
\]

where \( \varepsilon \) is positive or negative with respect to to that \( \varepsilon(x') \) positive or negative, respectively.

Similarly, the broken line \( PHF_1 \) can be realised in the cases when we have either consider \( r_3 \) with

\[
|PH| = \tau = a + \sqrt{a^2 - \mu} + \sqrt{a^2 - \nu} - \sqrt{a^2 - f^2}
\]

or \( r_4 \) with

\[
|PH| = \tau = a + \sqrt{a^2 - \mu} - \sqrt{a^2 - \nu} - \sqrt{a^2 - f^2},
\]

respectively.

Since we have that

\[
|HF_1| = \sqrt{(\varepsilon((C_2)_x)\sqrt{a^2 - b^2}\frac{\sqrt{a^2 - f^2}}{\sqrt{a^2 - c^2}} + \sqrt{a^2 - c^2})^2 + (\varepsilon((C_2)_x)\sqrt{a^2 - c^2}\frac{\sqrt{a^2 - b^2}}{\sqrt{a^2 - c^2}})^2} =
\]

\[
= \sqrt{a^2 - b^2} + \varepsilon((C_2)_x)\sqrt{a^2 - f^2},
\]

and we get for the polygonal length of \( PHF_1 \)

\[
|PH| + |HF_1| = a + \sqrt{a^2 - \mu} + \varepsilon\sqrt{a^2 - \nu} + \sqrt{a^2 - b^2}
\]

if \( H \) and \( F_1 \) corresponding to distinct branches of the focal hyperbola and \( \varepsilon \) is positive or negative with respect to that \( P \) and \( F_1 \) are on the same or opposite halfspaces of the \( yz \) plane. If \( H \) and \( F_1 \) corresponding to the same branch of the focal hyperbola we have

\[
|PH| + |HF_1| = a + \sqrt{a^2 - \mu} - \varepsilon\sqrt{a^2 - \nu} - \sqrt{a^2 - b^2},
\]

where again \( \varepsilon = 1 \) if and only if \( P \) and \( F_1 \) are on the same half-space of the \( yz \) plane.
Comparing the above results with the assumption of the statement we get that the optimal polygonal length is

$$|PE| + |EG_2| + |PH| + |HF_1| = 2a + \sqrt{a^2 - c^2} - \sqrt{a^2 - b^2},$$

as we stated. □

**References**


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In mathematics, Euclidean space is the Euclidean plane and three dimensional space of Euclidean geometry, as well as the
generalizations of these notions to a Euclidean space—a space in which Euclid’s axioms and definitions apply; a metric
space that is linear and finite dimensional. Hypernyms: metric space • * * * noun Usage: often capitalized E : the space to which
Euclid’s axioms and definitions (as of a) • Useful english dictionary. Euclidean space noun a) Ordinary two or three dimensional
space, characterised by an infinite extent along each dimension and a constant distance between any pair of parallel lines. b) Any real
vector space on which a real valued inner product (and, consequently a) Keywords: Euclidean space, subset search, clustering, NP-
hardness, pseudopoly-nomial algorithms. 1 Introduction. The subject of study in the paper is one of the subset choice problems in a finite
set of Euclidean vectors (points). The aim of the study is analysis of its complexity status and investigation of algorithmic approaches for
it. The paper is organized as follows. In the next section the formal definition of the currently studied and related problems are given;
some examples of applications (origins) of the studied problem are also presented. In Section 3 we prove two theorems. Copyrightâ€”by the paper’s authors. Copying permitted for private and academic purposes. In: A. Kononov et al. (eds.): DOOR 2016,
Vladivostok, Russia, published at http://ceur-ws.org. The paper deals with hyper-quadrics in the real projective 4-space. According to [1]
there exist 11 types of hypersurfaces of 2nd order, which can be represented by projective normal forms with respect to a polar simplex
as coordinate frame. By interpreting this frame as a Cartesian frame in the (projectively extended) Euclidean 4-space one will receive
sort of Euclidean standard types of hyper-quadrics resp., hypersurfaces of 2nd order: the sphere as representative of hyper-ellipsoids,
equilaterial hyper-hyperboloids, and hyper-cones of revolution.